



廣東工業大學  
Guangdong University of Technology

广东工业大学

## 第五章 正弦波振荡器

信息工程学院

李志忠

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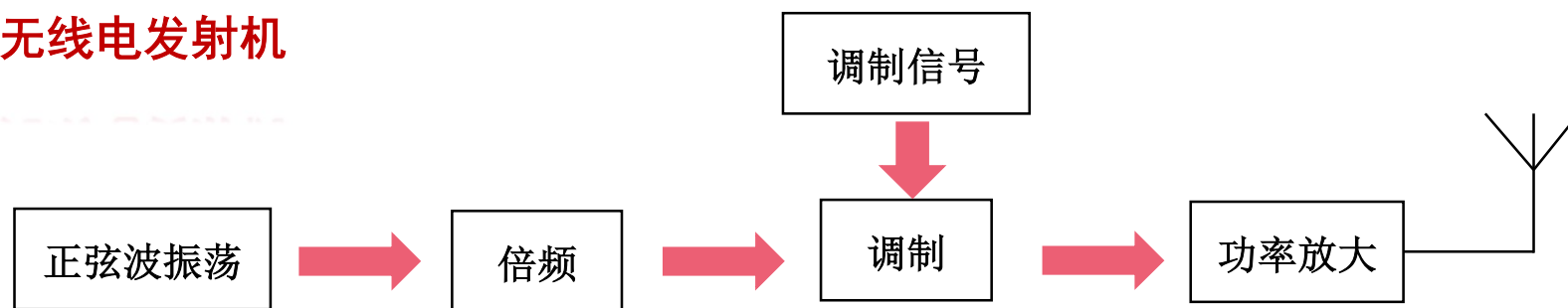
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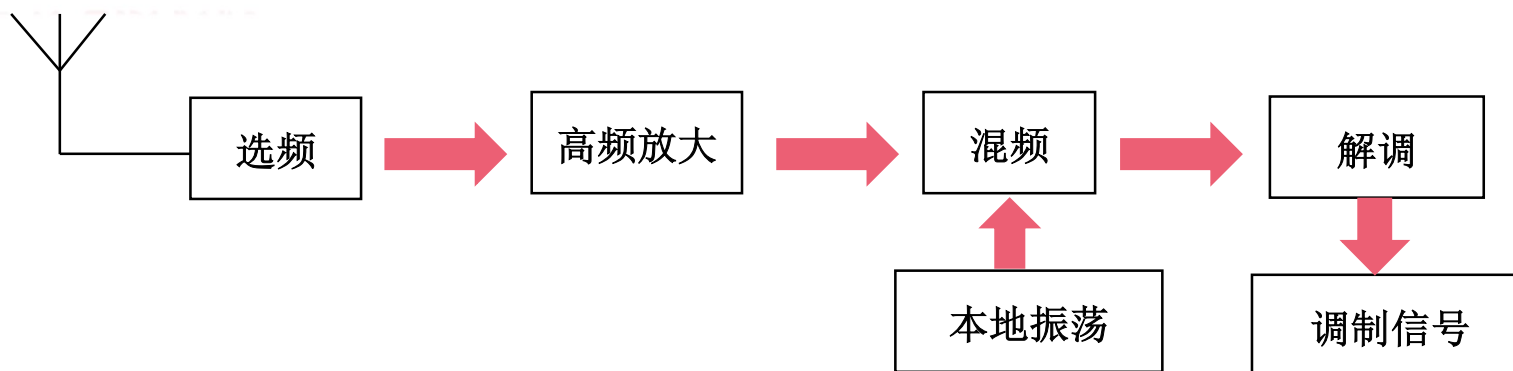
5.3 振荡器的频率稳定原理和高稳定度的  $LC$  振荡器

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## 无线电发射机



## 无线电接收机



## 振荡器？

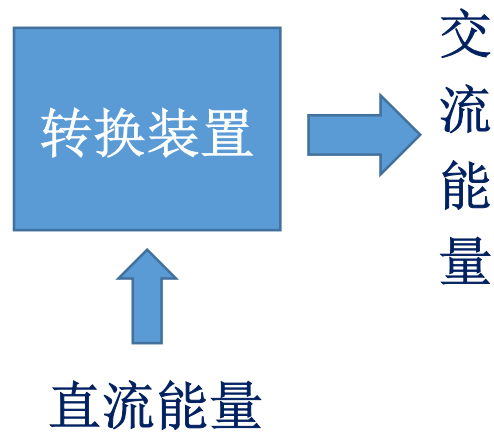
**振荡器** (oscillator)：没有输入信号，只有直流电源供电，就可以产生并输出一定波形、一定频率和一定功率的交流信号的电路。

振荡器也可以看作是将直流电源**能量转换**为交流电能量的装置



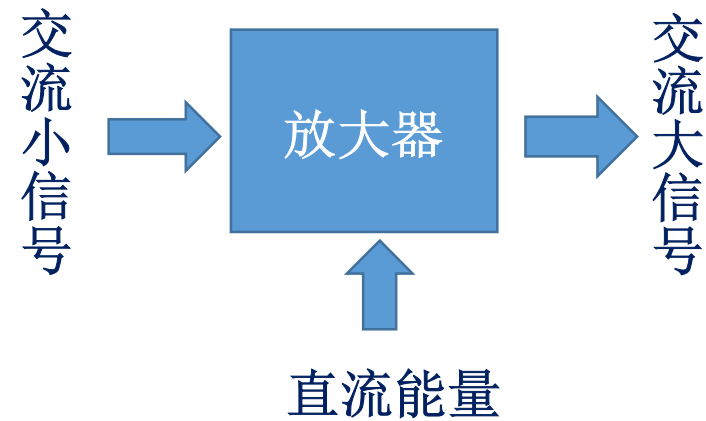
# 振荡器与放大器的区别

振荡器无信号输入  
自己产生交流信号



振荡器无中生有

放大器有信号输入  
将输入的交流信号放大



放大器照猫画虎

## —. Classification



## ◆ 5.1 反馈式振荡器的工作原理

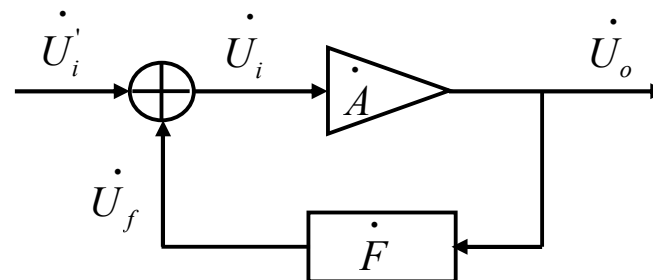
$$\dot{U}_o = \dot{A}\dot{U}_i \quad \dot{U}_f = \dot{F}\dot{U}_o$$

$$\ominus \quad \dot{U}_i = \dot{U}_i' - \dot{U}_f$$

$$\dot{U}_o = \dot{A}(\dot{U}_i' - \dot{U}_f) = \dot{A}\dot{U}_i' - \dot{A}\dot{F}\dot{U}_o$$

$$\therefore \frac{\dot{U}_o}{\dot{U}_i'} = \frac{\dot{A}}{1 + \dot{A}\dot{F}}$$

Negative Feedback Amplifier



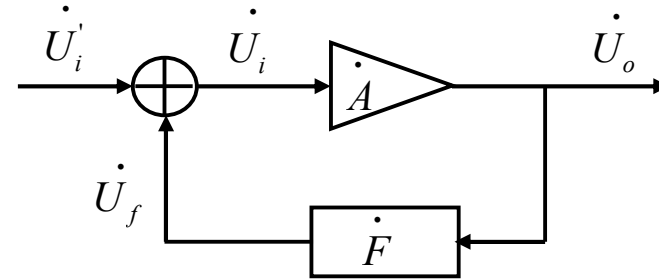
$$\oplus \quad \dot{U}_o = \dot{A}\dot{U}_i' + \dot{A}\dot{F}\dot{U}_o \quad \therefore \frac{\dot{U}_o}{\dot{U}_i'} = \frac{\dot{A}}{1 - \dot{A}\dot{F}}$$

$$\dot{A}\dot{F} = 1 \quad \frac{\dot{U}_o}{\dot{U}_i'} = \infty$$

## ◆ 5.1.1 平衡条件

$$\dot{A}\dot{F} = 1 = \frac{\dot{U}_o}{\dot{U}_i} \cdot \frac{\dot{U}_f}{\dot{U}_o} = \frac{\dot{U}_f}{\dot{U}_i}$$

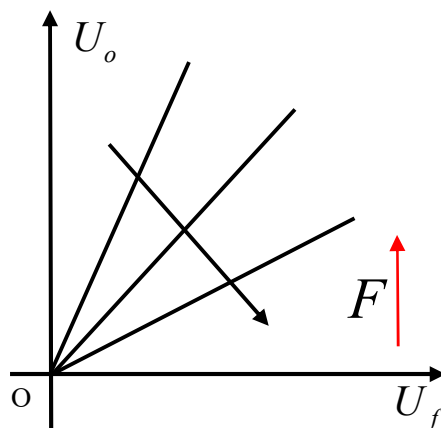
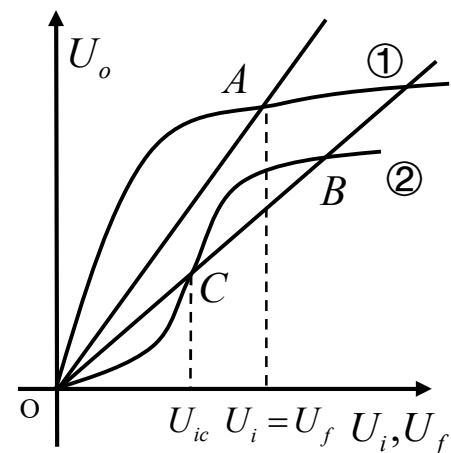
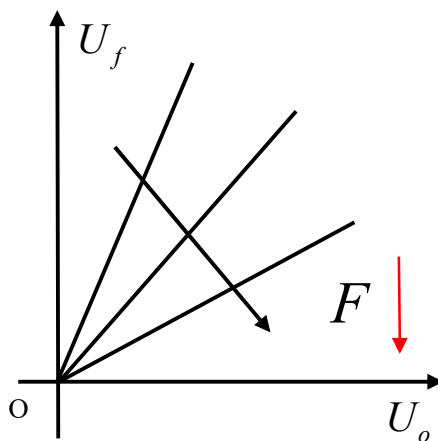
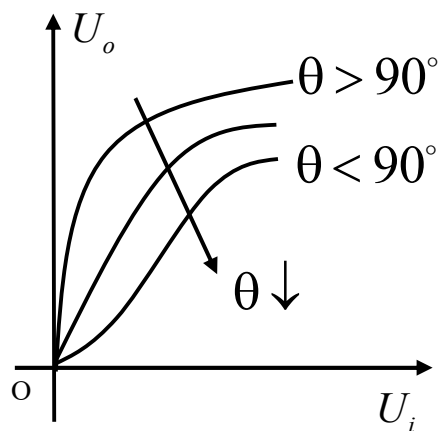
$$\begin{cases} \dot{U}_f = \dot{U}_i \\ \dot{U}_i = \dot{U}_i' + \dot{U}_f \end{cases} \Rightarrow \dot{U}_i' = 0$$



$$\dot{A}\dot{F} = 1 \Rightarrow \begin{cases} AF = 1 \Leftrightarrow U_f = U_i & \text{振幅平衡条件} \\ \varphi_A + \varphi_F = 2n\pi, n = 0, 1, 2, \dots & \text{相位平衡条件} \end{cases}$$



## ◆◆ 1. 振幅平衡条件

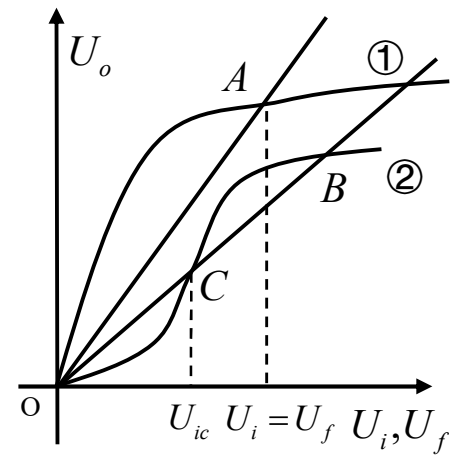
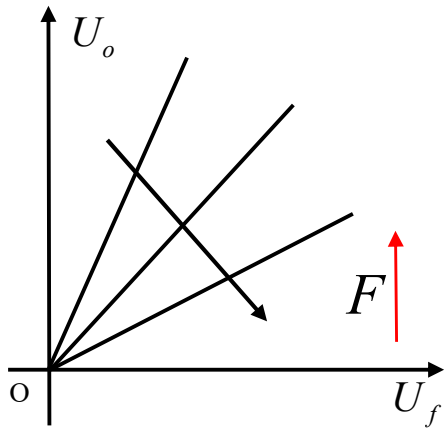
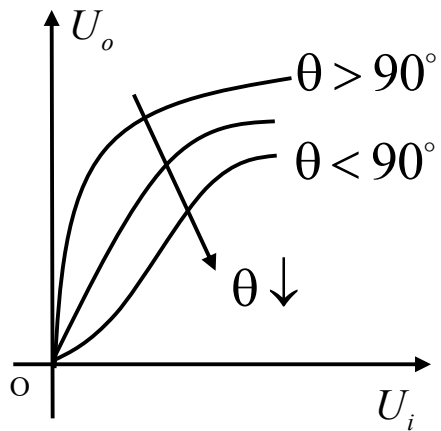


$$AF = 1 \Leftrightarrow U_f = U_i \quad \text{振幅平衡条件}$$

振幅平衡条件：反馈电压等于输入电压幅值；

$U_f = U_i$  的点即为满足振幅平衡条件的平衡点，

相应的  $U_o$ ，就是振荡器产生的电压振幅



$$\left. \begin{aligned} \dot{U}_o &= A \dot{U}_i \\ \dot{U}_o &= \frac{\dot{U}_f}{F} \end{aligned} \right\}$$

$$\left. \begin{aligned} A F \dot{U}_i &= \dot{U}_f \\ \dot{U}_i &= \dot{U}_f \end{aligned} \right\} \quad AF = 1$$

## ◆ 2. 相位平衡条件

$\varphi_A + \varphi_F = 2n\pi$  反馈电压  $\dot{U}_f$  与输入电压  $\dot{U}_i$  同相，即 **正** 反馈

$$\dot{U}_o = \dot{I}_L \dot{Z}_L(\omega) = \dot{g}_m \dot{U}_i \dot{Z}_L(\omega)$$

$$A = \frac{\dot{U}_o}{\dot{U}_i} = \frac{\dot{g}_m \dot{U}_i \dot{Z}_L(\omega)}{\dot{U}_i} = \dot{g}_m \dot{Z}_L(\omega) = A e^{i\varphi_A}$$

$$\therefore \varphi_A = \varphi_Y + \varphi_Z$$

$$f_0 \ll f_T \quad \dot{g}_m \ll g_m \quad \varphi_Y = 0$$

$\varphi_Y$  : 集电极电流基波分量

$\varphi_Z$  : 负载的相角

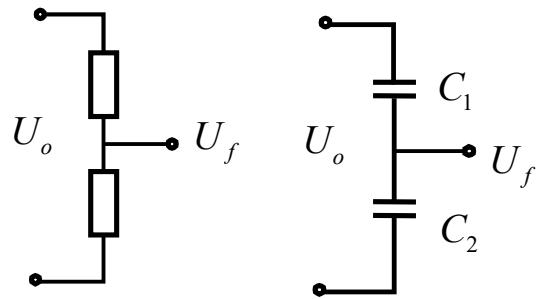
$$n = 0 \quad \varphi_A + \varphi_F = 0 \quad \therefore \varphi_A = -\varphi_F$$

$$\varphi_A + \varphi_F = \varphi_Y + \varphi_Z + \varphi_F = 0$$

若令  $\varphi_Y + \varphi_F = \varphi_{YF}$ ，则  $\varphi_Z = -\varphi_{YF}$

$$\varphi_A + \varphi_F = \varphi_Y + \varphi_Z + \varphi_F = 0 \quad \varphi_Y + \varphi_F = \varphi_{YF} \quad \varphi_Z = -\varphi_{YF}$$

$\varphi_F$  :



$$F = \frac{U_f}{U_o} = \frac{i \frac{1}{j\omega c_2}}{i \frac{1}{j\omega c_2 // c_1}} = \frac{c_2 // c_1}{c_2} = \frac{c_1}{c_2 + c_1}$$

$$\therefore \varphi_F = 0$$

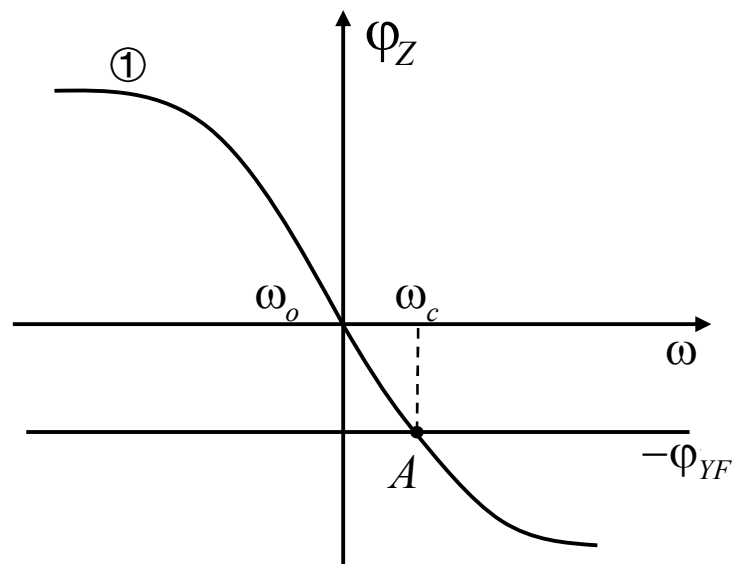
**一般情况：**晶体管少数载流子在通过基区有效宽度时，总需要一定的扩散时间，即 $I_c$ 总滞后于 $U_i$

$$\therefore \varphi_Y < 0 \quad \therefore \varphi_{YF} = \varphi_Y + \varphi_F \neq 0 \quad \therefore \varphi_Z = -\varphi_{YF} \neq 0$$

$\therefore$  谐振时呈现纯阻  $\therefore$  失谐工作即：  $\omega_c \neq \omega_o$

$\omega_c$  : 电路参数决定的振荡频率  $\omega_o$  : 回路谐振频率

$$\because (\omega_c - \omega_o) \downarrow$$
$$\therefore \omega_c \approx \omega_o$$



LC并联振荡回路  
负载相角与频率的关系

## ◆ 5.1.2 稳定条件 stabilization Condition

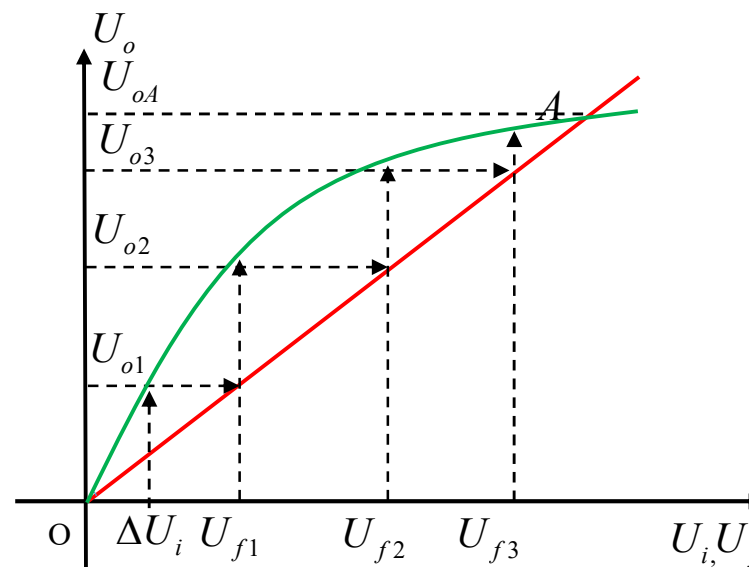
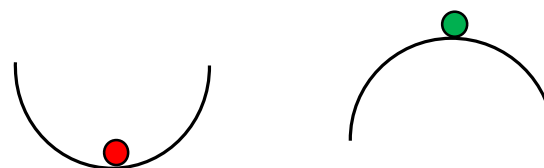
### 1. 振幅稳定条件

$$\theta \geq 90^\circ$$

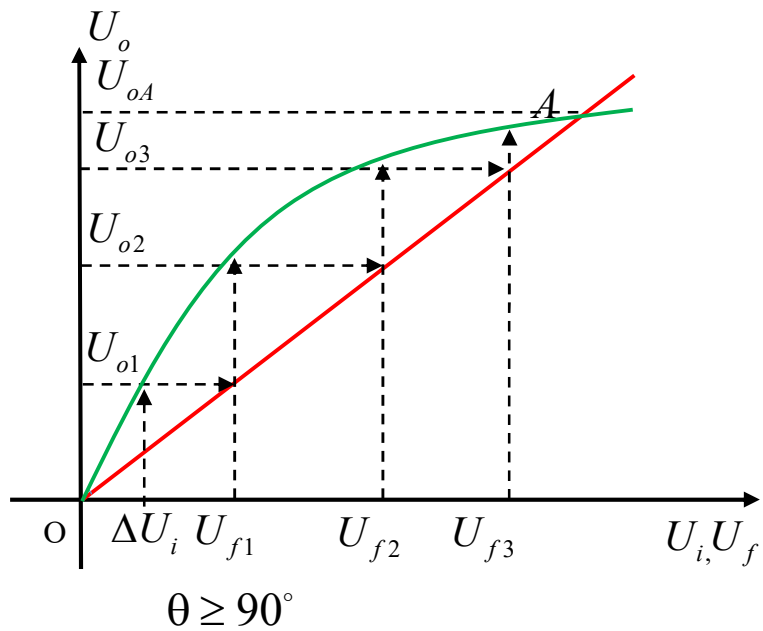
放大特性与反馈特性有两个交点O、A

电源接通瞬间 $\dot{U}_i = 0, \dot{U}_o = 0$ 外界电磁感应在放大器输入端感应电压 $\Delta U_i$ ，放大器输出 $U_{o1}$ ，经过反馈网络，反馈电压 $U_{f1}$ ，由于 $U_{f1} > \Delta U_i$ ，振荡器就会脱离原点而振荡起来。

若因外界因素振荡偏离A点，仍可返回



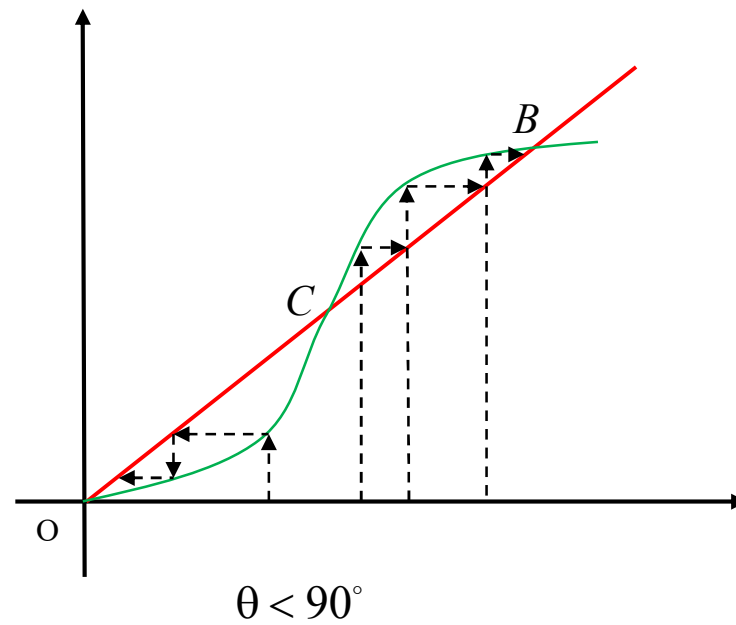
$\theta \geq 90^\circ$  的放大特性与反馈特性



A 稳定点

Soft Self Excitation

软自激



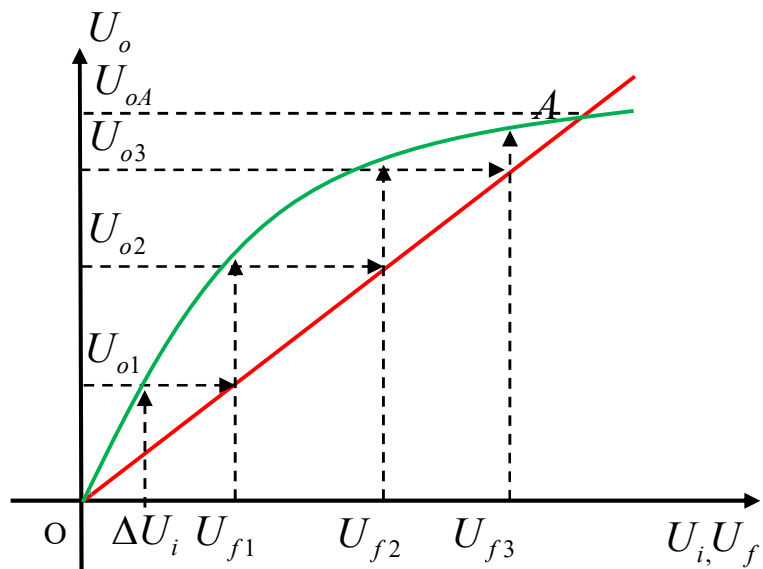
O、B 稳定点；C 非稳定点

初始为 O，不起振

$U_i > U_c$  自动起振

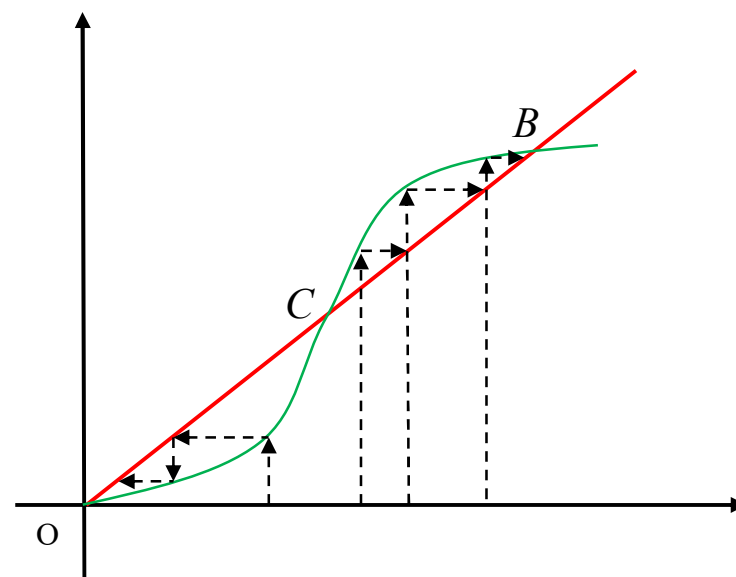
Hard Self Excitation

硬自激



$\theta \geq 90^\circ$

A 稳定点



$\theta < 90^\circ$

O、B 稳定点；C 非稳定点

稳定：放大特性斜率小于反馈特性斜率

$$\left. \frac{\partial U_o}{\partial U_i} \right|_p < \left. \frac{\partial U_o}{\partial U_f} \right|_p$$

$$\frac{\partial U_o}{\partial U_i} \frac{\partial U_f}{\partial U_o} < 1$$

$$\left. \frac{\partial U_f}{\partial U_i} \right|_p < 1$$



$$\frac{\partial U_f}{\partial U_i} \Big|_p < 1 \quad \frac{\partial U_f}{\partial U_i} = \dot{F} \dot{U}_i \frac{\partial \dot{A}}{\partial \dot{U}_i} + \dot{A} \dot{U}_i \frac{\partial \dot{F}}{\partial \dot{U}_i} + \dot{A} \dot{F} \frac{\partial \dot{U}_i}{\partial \dot{U}_i} < 1$$

$$U_f = \dot{A} \dot{F} \dot{U}_i$$

平衡点:

$$\dot{A} \dot{F} = 1 \quad \dot{F} \dot{U}_i \frac{\partial \dot{A}}{\partial \dot{U}_i} + \dot{A} \dot{U}_i \frac{\partial \dot{F}}{\partial \dot{U}_i} < 0 \quad \dot{F} \frac{\partial \dot{A}}{\partial \dot{U}_i} + \dot{A} \frac{\partial \dot{F}}{\partial \dot{U}_i} < 0$$

$$\left\{ \begin{array}{l} F = \text{常数} \\ A = \text{常数} \end{array} \right. \quad \begin{array}{l} \frac{\partial \dot{F}}{\partial \dot{U}_i} = 0 \\ \frac{\partial \dot{A}}{\partial \dot{U}_i} = 0 \end{array} \quad \begin{array}{l} \therefore \dot{F} \frac{\partial \dot{A}}{\partial \dot{U}_i} < 0 \\ \therefore \dot{A} \frac{\partial \dot{F}}{\partial \dot{U}_i} < 0 \end{array}$$

内稳幅条件  
非线性放大器

外稳幅条件  
非线性反馈网络

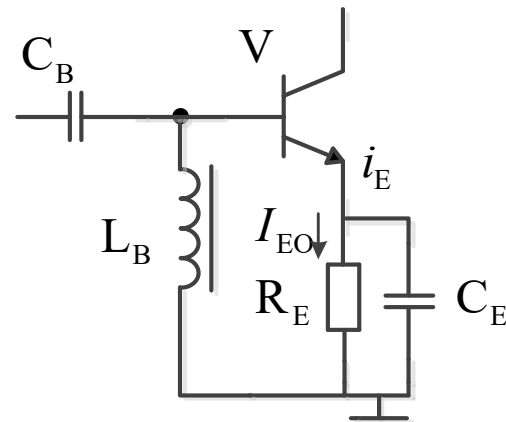
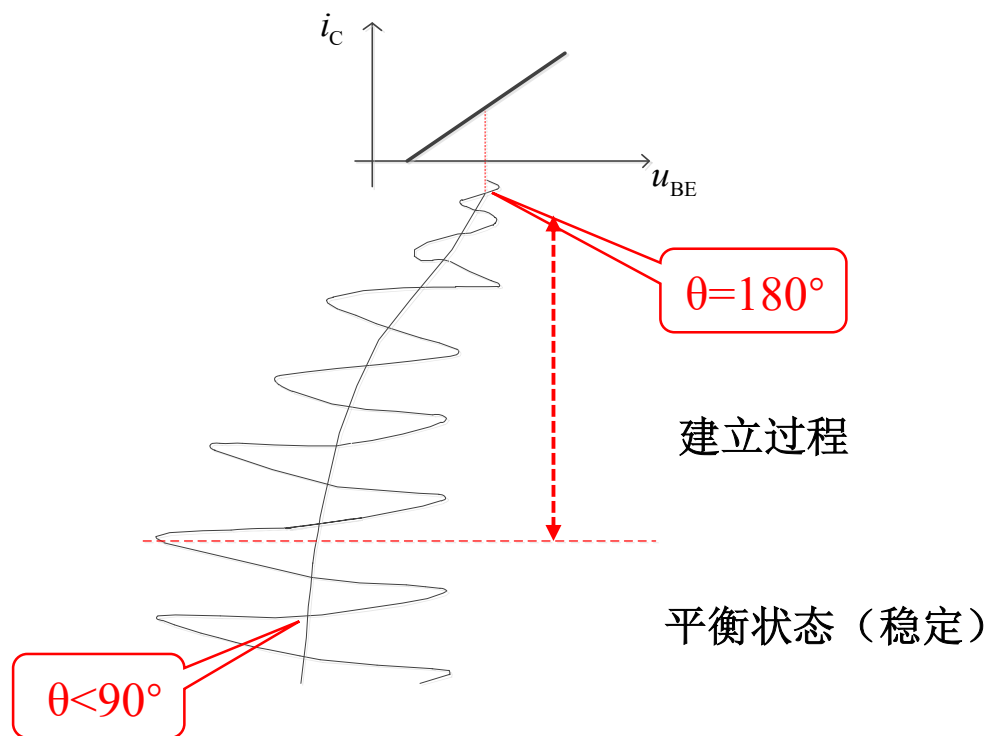
稳定:  $\theta \geq 90^\circ$  Soft Self Excitation 软自激

$\theta < 90^\circ$  Hard Self Excitation 硬自激

自动起振: 电源接通瞬间A类(  $\theta = 180^\circ$  )

$U_i \uparrow \quad U_o \uparrow \quad \theta \downarrow$

$\theta < 90^\circ$  (C类) 达到平衡  $\dot{A}\dot{F} = 1$



发射极自给偏置电路

## 2. 相位稳定条件

$$U = U_m \sin(\omega t + \varphi_0)$$

$$\omega' = \frac{d\varphi(t)}{dt} = \frac{d(\omega t + \varphi_0)}{dt}$$

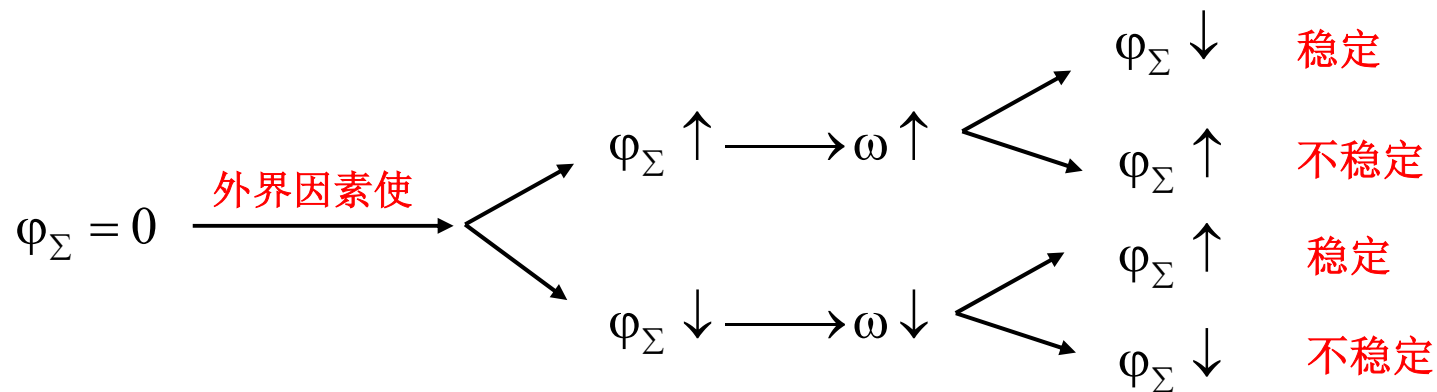
$$\varphi_0: \text{常数} \quad \omega' = \omega$$

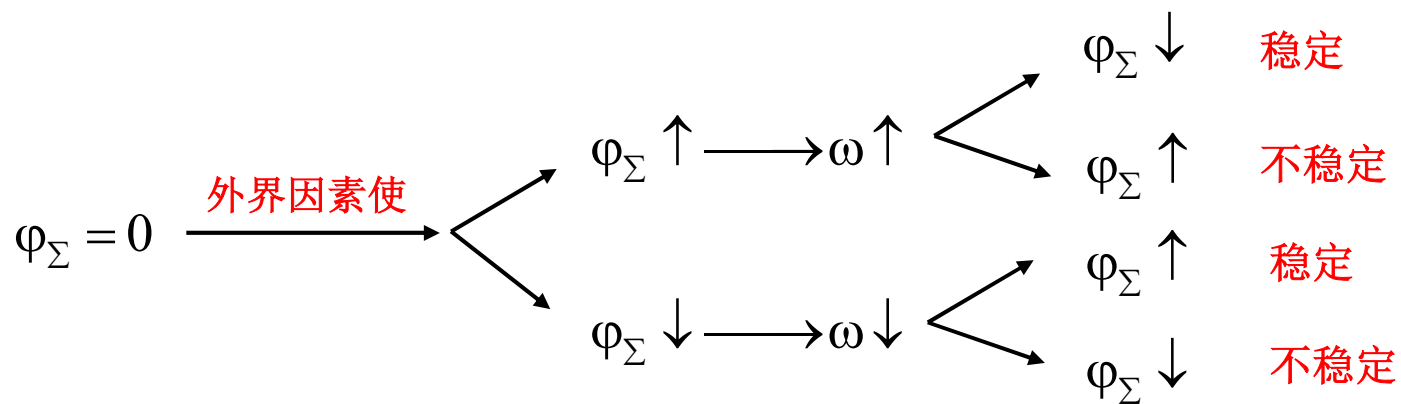
$$\varphi_0: \text{非常数} \quad \omega' = \omega + \frac{d\varphi_0}{dt} = \omega + \Delta\omega$$

$$\therefore \varphi \uparrow \quad \omega \uparrow \quad f \uparrow$$

相位超前

频率增大

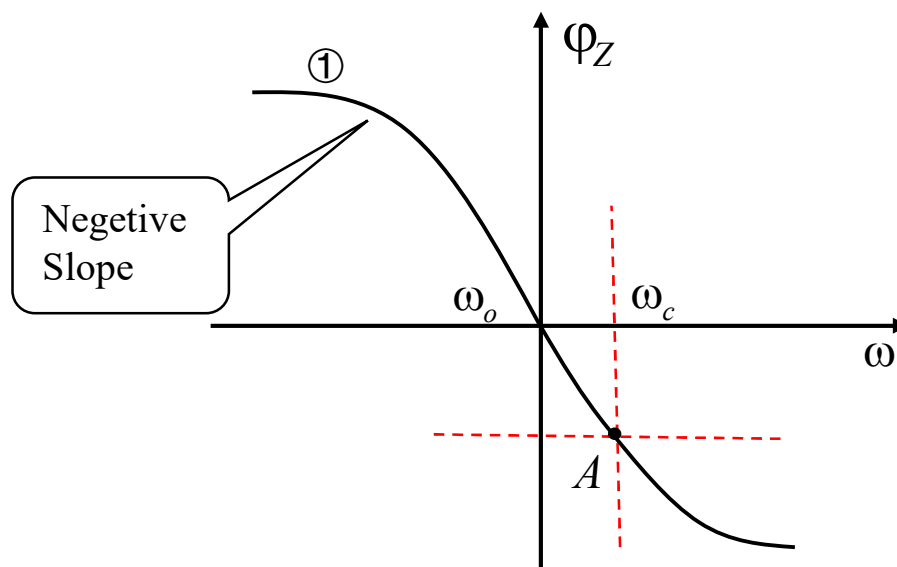




相位稳定条件:  $\frac{\partial \varphi_{\Sigma}}{\partial \omega} \Big|_p = \left( \frac{\partial \varphi_Y}{\partial \omega} \Big|_p + \frac{\partial \varphi_F}{\partial \omega} \Big|_p + \frac{\partial \varphi_Z}{\partial \omega} \Big|_p \right) < 0$

窄带可认为:  $\frac{\partial \varphi_F}{\partial \omega} \approx 0$        $\frac{\partial \varphi_Y}{\partial \omega} \approx 0$

相位稳定条件:  $\frac{\partial \varphi_Z}{\partial \omega} \Big|_p < 0$



### ◆ 5.1.3 起振条件

$$\begin{cases} AF > 1 & U_f > U_i & \text{振幅起振条件} \\ \varphi_{\Sigma} = 2n\pi & & \text{相位起振条件} \end{cases}$$

起始  $U_i$  小，工作于A类，自起振

∴ 起振用小信号微变等效电路分析法

**起始状态**

$$\dot{A}F > 1$$

工作于 A 类， $\theta \geq 90^\circ$

小信号、线性

微变等效电路分析法

**稳定状态**

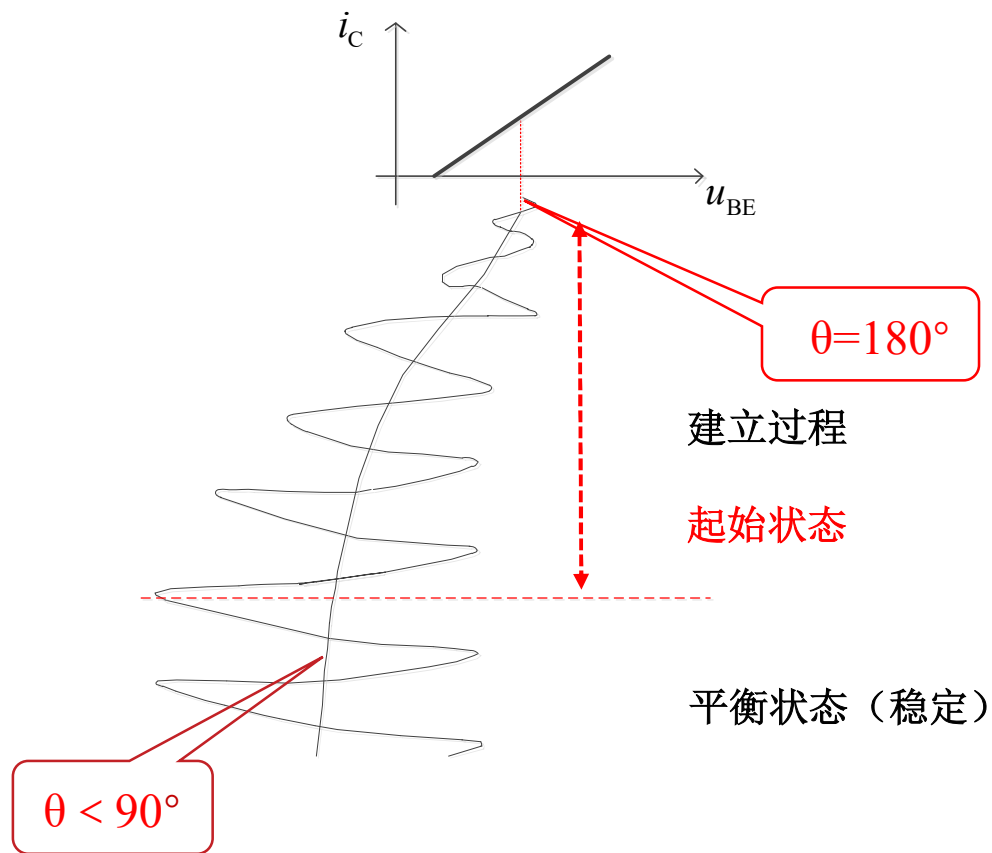
$$\dot{A}F = 1$$

工作于 C 类， $\theta < 90^\circ$

大信号、非线性

不能用微变等效电路分析法

**Y参数等效电路分析法**



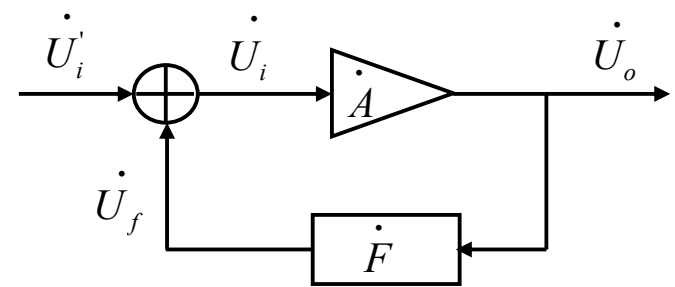
$$\dot{A}\dot{F} > 1$$

工作于 A 类,  $\theta \geq 90^\circ$   
 小信号、线性  
 微变等效电路分析法

$$\dot{A}\dot{F} = 1$$

工作于 C 类,  $\theta < 90^\circ$   
 大信号、非线性  
 不能用微变等效电路分析法  
**Y 参数等效电路分析法**

振荡器 振荡条件	平衡	振幅平衡	$AF=1$
		相位平衡	$\varphi_{\Sigma} = 2n\pi$
	稳定	振幅稳定	$F \frac{\partial \dot{A}}{\partial \dot{U}_i} + A \frac{\partial \dot{F}}{\partial \dot{U}_i} < 0$
		相位稳定	$\frac{\partial \varphi_{\Sigma}}{\partial \omega} < 0$
	起振	振幅起振	$AF > 1$
		相位起振	$\varphi_{\Sigma} = 2n\pi$



- 振荡器组成
- 放大器:** BJT、FET、差分放大器、运算放大器等
  - 反馈网络:** RC 移相、电容分压、电感分压、变压器耦合或电阻分压网络等
  - 选频网络:** LC、RC、晶体滤波器等

**谢谢!**